

# ECSx3050/StSt/NUM/HV

1005685

## Technical Specifications

<b>Size and Dimensions</b>	
footprint; height	30 mm x 50 mm; 9.5 mm
maximum installation space	30 mm x 81.6 mm; 9.5 mm
weight (stainless steel version)	90 g
height	9.5 mm
cable	50 cm cable with connector
<b>Materials</b>	
positioner body	stainless steel
actuator	PZT ceramics
connecting wires	copper, jacket: RT: PTFE, HV/UHV: fiberglass
<b>Coarse Positioning Mode</b>	
travel range (step mode)	30 mm
maximum drive velocity @ 300 K	4.5 mm/s
input voltage range	0 - 45 V
<b>Fine Positioning Mode</b>	
fine linear positioning range @ 300 K	1.6 $\mu$ m
fine positioning resolution	sub-nm
input DC voltage range	0 - 45 V
<b>Position Encoder</b>	
readout mechanism	optoelectronic sensor
encoded travel range	entire travel
sensor resolution	1 nm
sensor power (when measuring)	300 mW
repeatability	50 nm (bidirectional)
<b>Load (@ ambient conditions)</b>	
maximum load	2 kg
maximum dynamic force along the axis	1 N
<b>Error Motion</b>	
roll E_AX	specified* 1.25 mrad (expected** < 0.25 mrad)
pitch E_BX	specified* 1.75 mrad (expected** < 1 mrad)
yaw E_CX	specified* 1.25 mrad (expected** < 0.4 mrad)
y-Straightness E_YX	specified* 4 $\mu$ m (expected** < 3 $\mu$ m)
z-Straightness E_ZX	specified* 8 $\mu$ m (expected** < 6 $\mu$ m)
*	specified: guaranteed for every positioner
**	expected: typically met by most positioners
<b>General Specifications</b>	
environment	high vacuum

